

Lighting up the future of productive agriculture

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Sustainable Food • Zero Chemicals • Zero Emissions • Zero Till

## The Challenge



Weeds compete with crops & therefore need to be controlled.



£30bn / year spent globally on herbicides putting 1 million tonnes into the environment.



Herbicide resistant weeds reported in 92 101 crops in 72 countries.

Farmers are faced with a choice:

#### **EITHER**

use chemicals;

#### OR

- increase cost of food production
- increase GHG emissions
- not achieve Net Zero.





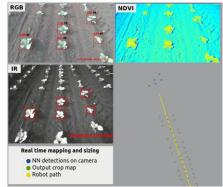
### The Solution

Earth Rover have developed <u>CLAWS</u>.

- Concentrated
- Light
- Autonomous
- Weeding &
- Scouting

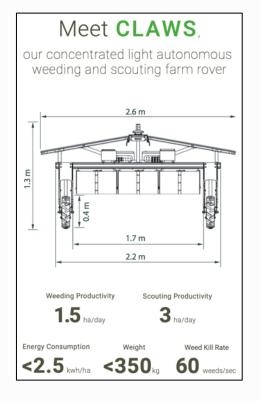
A lightweight, autonomous field robot utilising state of the art image processing, Artificial Intelligence (AI) and GNSS RTK satellite navigation.







### The Solution







Precise, efficient, eye-safe

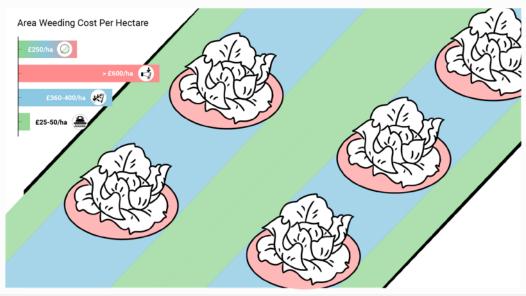


Environmentally friendly – battery & solar power

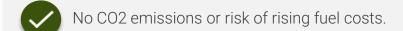


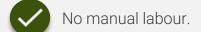
Gathers real-time Crop Data

## Why are we different?











No mechanical crop damage.



Increased operational hours per season.



Crop data at per plant level.

### Concentrated Light Weed Control



"Lightweeder controls different types of weeds including chemically (ALS) resistant weeds."

NIAB Independent testing



Figures 3a. A visual comparison of the control achieved against herbicide sensitive (left) and herbicide resistant (right) populations of Italian rye-grass. Figure 3b. A visual comparison of the control achieved against two sizes of Bur chervil, a dicot species.

### Al Weed Detection





### Al Weed Meristem Detection





### Field trials on Lettuce









# Targeted Weeds







# High Weed Density Testing



# Field Trials

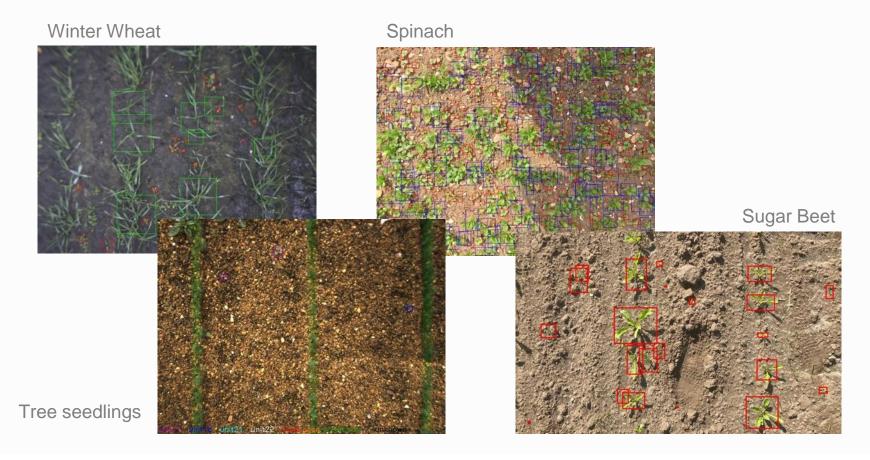








## The future potential?



### Path to Market



2024

2025

2026

- V2 CLAWS & User Interface Development.
- Build 5 more CLAWS units.
- Expand R&D & Operations team.
- 5 Pilot Weeding and Scouting Trials
- Customer/ Partner Demonstration Events.

- Independent full season validation.
- V2 CLAWS Launch
- Build facility for 200 units per annum
- Ramp Sales through RaaS,
  Distributor Network, Collaboration.
- Build and deployment of 200 units.

### Sites & Locations

Our sites span across two countries: the United Kingdom and Spain, strategically positioned to drive pioneering agricultural innovation.



- Earth Rover's registered address at the UK Agri-tech Centre
- Testing and trials in collaboration with Pollybell Farms

- R&D hub at Parc UPC-RDIT, Castelldefels
- Testing and trials at Parc UPC Agròpolis







Thank you

### Disclaimer

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### Q & A / Discussion



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#### Lighting up the future of productive agriculture

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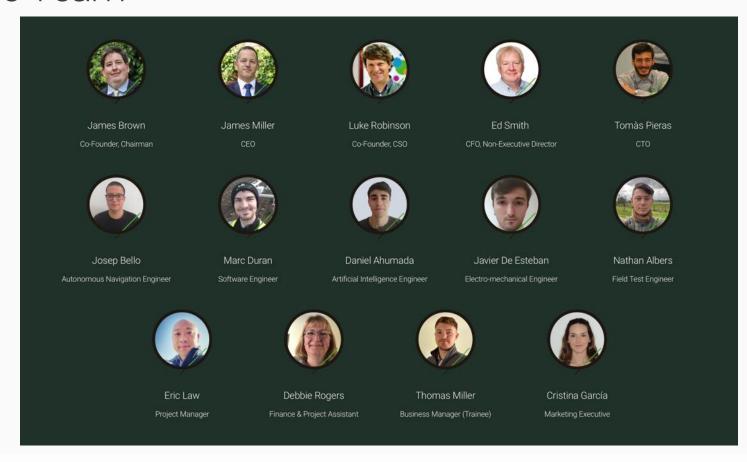
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### The Team



### Concentrated Light Weed Control

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NIAB Independent testing

Species	Common Name	Species Class	Archetypal Biotype	Plant size tested	Size (cm) [height for monocots; width for dicots]
Alopecurus myousroides	Black-grass	Monocot	Small leaf	Small	2-4
Poa annua	Annual Meadow Grass	Monocot	Small leaf	Small and large	2-3 / 4-6
Lolium multiflorum (sensitive)	Italian rye- grass (sensitive)	Monocot	Medium leaf	Large	6-7
Lolium multiflorum (ALS resistant)	Italian rye- grass (resistant)	Monocot	Medium leaf	Small and large	3-4 / 6-7
Avena sativa	Oat	Monocot	Large leaf	Small and large	2-3 / 4-7
Allium spp.	Onion	Monocot	Small leaf, upright	Small	3-5
Anthriscus caucalis	Bur chervil	Dicot	Medium leaf, flat	Small and large	2-3 / 4-7
Stellaria media	Chickweed	Dicot	Small leaf, sprawling	Small and large	0.5-1/2-3
Tripleurospermum inodorum	Mayweed	Dicot		Small and large	1-2 / 2-4

Table 1. Species list used in the study

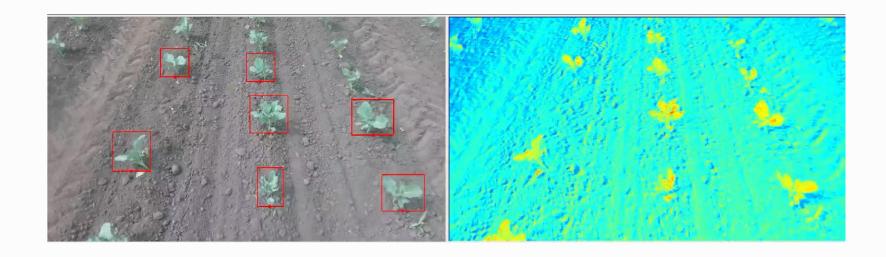


Figures 3a. A visual comparison of the control achieved against herbicide sensitive (left) and herbicide resistant (right) populations of Italian rye-grass. Figure 3b. A visual comparison of the control achieved against two sizes of Bur chervil, a dicot species.

## Why are we different?



## Real time Al Crop Detection



## CLAWS - Scouting Intelligence

#### **UK & Spain Scouting Pilots**

Crop Scouting, Weed Detection and Weed Density Mapping

